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* Program Number: 68K Monitor for S100Computers.com
* Written by : John Monahan
* Date Created : 11/11/2011
* Description : Basic monitor for 68K S-100 board
*
*   'A=Memmap      C=XMODEM(Bin)  D=Disp RAM      E=Echo          F=Fill RAM'
*   'G=Goto RAM    H=Math           I=Time          K=Menu          L=Test Ints'
*   'M=Move RAM    N=IDE Menu     Q=Port I/O      U=Serial Test  S=Subs RAM'
*   'T=Type RAM    V=Verify RAM   X=Signals       Y=Patch         Z=Back to Z80'
*
*-----
;          V1.5      03/07/2012 ;Corrected line length display of RAM (D & T Commands)
;          V1.6      03/07/2012 ;Added initilization of Interrupt routines in low RAM
;          V1.7      03/08/2012 ;Add test interrupts routine, "L" CMD.
;          V1.8      03/09/2012 ;Code to switch back to Z80, and hardware signals anal
;          V1.9      03/18/2012 ;Added IDE Board Diagnostic Section
;          V1.91     03/27/2012 ;Substitute RAM redone
;          V2.0      04/02/2012 ;Added IDE Menu Items and Y command
;          V2.1      04/26/2013 ;Fixed numerous small bugs, RAM display map,D,F,M X co
;          V2.2      04/27/2013 ;Display RAM (D CMD) also displays ASCII
;          V2.3      04/23/2014 ;Allow output to 16 bit ports (>0FFH), DMA1* port swit
;          V2.4      04/30/2014 ;Cleanup console I/O routines, add serial port I/O
;          V2.5      05/2/2014  ;Added XMODEM .bin file download capabilities over ser
;          V2.6      06/12/2014 ;Corrected QO/QI port bug
;          V3.0      7/27/2020  ;Damian Wildie corrections and addition of working IDE
;          V3.1      2/1/2021   ;Corrected numerous small errors. Sec Writes corercted
;          V3.11     2/1/2021   ;Made commands the same as for 68030 Monitor..
;          V3.12     2/8/2021   ;Corrections to Drive ID info
;
;
;
;
;Programming a Wellon VP-290 with 28C256 EEPROMS.
;Assemble and make a S68 file (Project Menu for EASy68K)
;Load first, even byte in dropdown menu for "File Mode"
;For "From File Address(Hex) enter FD0000 (Note "To Buffer Address (HEX) is 0)
;File Size is 8000 (for X28C256's)
;For "Auto Format Detect" use Motorola S
;Repeat, for second EEPROM using Odd Bytes for "File Mode"
;(Note for the 68030 Board only one PROM is needed).
;
;
;
BELL      EQU      $07
BLANK     EQU      $20
CR        EQU      $0D
LF        EQU      $0A
ESC       EQU      $1B
TAB       EQU      $09
SOH       EQU      1      ; For Modem etc.
EOT       EQU      4
ACK       EQU      6
NAK       EQU      $15
;
SIMULATOR EQU      0      ;Note, only one of the following 3 equates can be 1
S100_TEST  EQU      0      ;Set to 1 if using EASy68K Simmulator (Console I/O wil
ROM_CODE   EQU      1      ;Set to 1 if using S100 RAM (We will not use INT's for
                           ;Set to 1 for ROM code (We will not use INT's for cons
;
;Propeller Console IO S-100 board or SD SYSTEMS VIDIO BOARD FOR CONSOLE I/O(<---These must configu
KEYSTAT   EQU      $00FF0000
KEYIN     EQU      $00FF0001 ;Console input port. Normally the Propeller Driven S-1
KEYOUT    EQU      $00FF0001 ;Console output port. Normally the Propeller Driven S-
;
;----- THIS IS MY PORT TO OUTPUT DATA TO HP 4050T LASAR PRINTER (IMSAI 8PIO Board)
PRINTER_STATUS EQU      $00FF0005 ;IN, HP PARRELL PORT
PRINTER_OUT    EQU      $00FF0005 ;OUT

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COUNTS_SEC	EQU	\$18	
COUNTS_MIN	EQU	1092	
COUNTS_HOUR	EQU	\$07	; Seems this value is used with AT/CMOS chip (was 65543)
UPDATE_TIMER			EQU \$80
CMOS_SECONDS			EQU \$0 ;RAM offsets for CMOS Registers
CMOS_MINUTES			EQU \$2
CMOS_HOURS	EQU	\$4	
IFEQ SIMMULATOR			; If SIMMULATOR = 0 (Normal EEPROM)
Patch_RAM	EQU	\$00F40000	; Location of Patch code area
ENDC			
IFNE SIMMULATOR			; If SIMMULATOR = 1 (For testing here within EASy68K &
Patch_RAM	EQU	\$00008000	
ENDC			

;----- S100Computers IDE BOARD PORT ASSIGNMENTS (30-34H)

; Ports for 8255 chip. Change these to specify where the 8255 is addressed,  
; and which of the 8255's ports are connected to which IDE signals.  
; The first three control which 8255 ports have the IDE control signals,  
; upper and lower data bytes. The forth one is for mode setting for the  
; 8255 to configure its ports, which must correspond to the way that  
; the first three lines define which ports are connected.

IDEportA	EQU	\$00FF0030	;lower 8 bits of IDE interface
IDEportB	EQU	\$00FF0031	;upper 8 bits of IDE interface
IDEportC	EQU	\$00FF0032	;control lines for IDE interface
IDECtrlPort	EQU	\$00FF0033	;8255 configuration port
IDEDrivePort		EQU \$00FF0034	;To select the 1st or 2nd CF card/
IDE_Reset_Delay	EQU	\$80	;Time delay for reset/initialization (~66 uS, with 8MHz
READcfg8255	EQU	%10010010	;Set 8255 IDEportC out, IDEportA/B input
WRITEcfg8255	EQU	%10000000	;Set all three 8255 ports output

; IDE control lines for use with IDEportC.

IDEa0line	EQU	\$01	;direct from 8255 to IDE interface
IDEa1line	EQU	\$02	;direct from 8255 to IDE interface
IDEa2line	EQU	\$04	;direct from 8255 to IDE interface
IDEcs0line	EQU	\$08	;inverter between 8255 and IDE interface
IDEcs1line	EQU	\$10	;inverter between 8255 and IDE interface
IDEWrline	EQU	\$20	;inverter between 8255 and IDE interface
IDERdline	EQU	\$40	;inverter between 8255 and IDE interface
IDErstline	EQU	\$80	;inverter between 8255 and IDE interface
			;

; Symbolic constants for the IDE Drive registers, this makes the  
; code more readable than always specifying the address pins

REGdata	EQU	IDEcs0line	
REGerr	EQU	IDEcs0line+IDEa0line	
REGsecnt	EQU	IDEcs0line+IDEa1line	
REGsector	EQU	IDEcs0line+IDEa2line+IDEa0line	
REGcylinderLSB	EQU	IDEcs0line+IDEa2line	
REGcylinderMSB	EQU	IDEcs0line+IDEa2line+IDEa0line	
REGshd	EQU	IDEcs0line+IDEa2line+IDEa1line ;(0EH)	
REGcommand	EQU	IDEcs0line+IDEa2line+IDEa1line+IDEa0line	; (0FH)
REGstatus	EQU	IDEcs0line+IDEa2line+IDEa1line+IDEa0line	
REGcontrol	EQU	IDEcs1line+IDEa2line+IDEa1line	
REGastatus	EQU	IDEcs1line+IDEa2line+IDEa1line+IDEa0line	

; IDE Command Constants. These should never change.

COMMANDrecal	EQU	\$10	
COMMANDread	EQU	\$20	
COMMANDwrite	EQU	\$30	

```

START:
    LEA      Signon,A2           ;Show we are alive
    BSR      PRINT_STRING

    BSR      SERIAL_INITILIZE_A ;Initialize Consoel-IO board Serial Port A
    BSR      SERIAL_INITILIZE_B ;Initialize Consoel-IO board Serial Port B
    LEA      SMSG,A2
    BSR      SPEAK_STRING        ;Speak out signon the message
;

    BSR      LOW_RAM_INITILIZE ;Initialize low RAM Int Vectors (for all modes)

    LEA      BeginRAM,A2         ;Initialize HIGH RAM to 0 (Used by IDE Routines)
    MOVE.L   # (EndRAM-BeginRAM), D0 ;START OF WORK RAM (PAST STACK)
    CLR.L   D1                  ;BYTES TO ZERO

ZERO_RAM:
    MOVE.B   D1, (A2) +          ;ZERO MEMORY
    SUBQ.L   #1, D0
    BNE     ZERO_RAM

loop:
    LEA      Prompt,A2           ;Show CR,LF, '>'
    BSR      PRINT_STRING
    CLR.L   D1                  ;Just to be on the safe side
    BSR      GETCHAR             ;Get a menu character (WITH ECHO)
    AND.B   #$7F,D1              ;Just to be safe, strip any potential parity bit
    BSR      TOUPPER              ;Lower case to Upper case for lookup table

    CMP.B   #'A',D1
    BLT     ERR
    CMP.B   #'Z',D1
    BGT     ERR
    SUB.B   #'A',D1
    LSL.L   #2,D1                ;X4 for offset into table
    LEA      ctable,A2            ;Start of cmd table
    MOVE.L   (A2,D1),A3          ;Add X4 offset
    JMP     (A3)

;-----
ERR:
    CMP.B   #CR,D1               ;If CR just return
    BEQ     loop
    MOVE.L   D1,-(A7)             ;> Save D1
    LEA      BadCmdMsg,A2         ;Non menu selection
    BSR      PRINT_STRING
    MOVE.L   (A7)+,D7              ;Put D1 in D7
    BSR      PUTLONG_D7
    LEA      H_MSG_CRLF,A2         ;H, then CR,LF
    BSR      PRINT_STRING
    BRA     loop                  ;Back to start for next command

;-----
SHOW_MENU:
    LEA      Menu,A2              ;Display this monitors commands on CRT
    BSR      PRINT_STRING          ;Menu string
    BRA     loop                  ;Back to start for next command

;-----
MEM_MAP:  MOVE.L   #0,A3           ;A Command. Do Memory Map. Pointer to RAM area A3=0
NEWLINE:  BSR      CRLF
    MOVE.L   A3,D7
    BSR      PUTLONG_D7           ;Print long value of D7
    MOVE.L   #64,D3              ;64 characters across per line
    MOVE.L   #$FFFFFF, D5

    MOVE.B   #BLANK,D1
    BSR      PUTCHAR

START1:   MOVE.L   (A3),D1           ;Is there RAM/ROM there
    NOT.L   D1
    MOVE.L   D1, (A3)              ;See if we can flip bits

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MOVE.L  (A7)+,A4          ;Next Show ASCII for this line, Back to origional RAM
MOVE.L  (A7)+,A3          ;Were stored above

BSR     SPACE
BSR     SPACE
MOVE.B  #16,D4            ;Count of characters across

PARMS_OK4: MOVE.B  (A3),D1      ;Get RAM byte to D1
              CMP.B  #' ',D1
              BLT    PRINT_DOT
              CMP.B  #$7F,D1
              BGE    PRINT_DOT
PARMS_OK6: BSR    PUTCHAR        ;Print character

ADDQ.L #1,A3
SUBQ.B #1,D4
TST.B  D4                 ;Have we done 16 characters across
BNE    PARMS_OK4

CMP.L  A3,A4              ;Are we done wit total data display yet
BLE   LOOP
BRA   PARMS_OK5

PRINT_DOT:
MOVE.B  #'.',D1
BRA    PARMS_OK6

;-----

FILL_RAM: BSR    GETLONG_D7      ;F Command. Fill RAM with one byte value
          CMP.B  #',',D2      ;Get start address
          BNE    ERROR         ;Is it valid
          MOVE.L D7,A3          ;Save in A3

          BSR    GETLONG_D7      ;End address
          CMP.B  #',',D2      ;Is it valid
          BNE    ERROR         ;Save in A4
          MOVE.L D7,A4          ;Else swap values

          CMP.L  A3,A4          ;If the same nothing to display
          BEQ    LOOP
          BGE    FILL_OK
          MOVE.L A3,A5
          MOVE.L A4,A3
          MOVE   A5,A4

FILL_OK: ADD.L  #1,A4          ;End + 1
          BSR    GETBYTE_D7      ;get Hex value in D7 (0-FF)
          CMP.B  #CR,D2          ;Is it valid
          BNE    ERROR

FILL_OK1: MOVE.B D7,(A3)        ;D7 to RAM
          ADDQ.L #1,A3
          CMP.L  A3,A4          ;Are we done yet
          BLE   LOOP
          BRA   FILL_OK1

;-----


SUBS_RAM: BSR    GETLONG_D7      ;S Command. Substitute RAM with one byte values
          CMP.B  #CR,D2          ;Get start address
          BNE    ERROR         ;Is it valid
          MOVE.L D7,A3          ;--- Save in A3 (also leave in A7)

SUBS_RAM2: BSR    CRLF           ;New line

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QUERY_PORT:
    CLR.L    D1          ;Just to be on the safe side
    BSR      GETCHAR    ;get a menu character
    BSR      TOUPPER    ;Lower case to Upper case

    CMP.B    #'I',D1     ;Is it a port input request
    BEQ     QUERY_IN
    CMP.B    #'O',D1     ;Is it a port output request
    BEQ     QUERY_OUT
    BRA     ERROR       ;Must be an error

QUERY_IN:   BSR      GETLONG_D7   ;Get (Byte only) Port Hex value in D7 (0-FF)
    TST.B    D3          ;Byte count > 0
    BEQ     LOOP
    CMP.B    #ESC,D2    ;If ESC then we abort
    BEQ     LOOP
    CMP.B    #CR,D2    ;If CR then we also abort
    BNE     ERROR
    MOVE.B   D7,D6      ;store in D6 (also in D7)

    LEA     PortMsg,A2   ;'Port xx'
    BSR      PRINT_STRING
    BSR      PUTBYTE_D6  ;Display Port value
    MOVE.B   #'H',D1     ;'H'
    BSR      PUTCHAR
    MOVE.B   #'=',D1     ; '='
    BSR      PUTCHAR

    MOVE.L   #$00FF0000,D6 ;Point to Port RAM area
    OR.B    D7,D6        ;OR in the hardware value
    MOVE.L   D6,A2        ;A2 now has port address
    MOVE.B   (A2),D6      ;Get value at port

    BSR      PUTBYTE_D6  ;Display Byte value
    MOVE.B   #'H',D1     ;'H'
    BSR      PUTCHAR
    MOVE.B   #' ',D1     ; ' '
    BSR      PUTCHAR
    MOVE.B   #'(',D1     ; '('
    BSR      PUTCHAR
    BSR      PUTBITS_D6
    MOVE.B   #'()',D1    ; ')'
    BSR      PUTCHAR
    BRA     LOOP

QUERY_OUT:  BSR      GETLONG_D7   ;Get Port value (value in D7, 0-FFFF)
    TST.B    D3          ;Byte count > 0
    BEQ     LOOP
    CMP.B    #ESC,D2    ;If ESC then we abort
    BEQ     LOOP
    CMP.B    #'',D2      ;If CR then we also abort
    BNE     ERROR
    MOVE.L   D7,D4      ;<<< Store (WORD) port # in D4

    BSR      GETBYTE_D7  ;Get data in D7 (0-FF)
    TST.B    D3          ;Byte count > 0
    BEQ     LOOP
    CMP.B    #ESC,D2    ;If ESC then we are done
    BEQ     LOOP
    CMP.B    #CR,D2    ;If CR then we are done
    BNE     LOOP
    MOVE.L   D7,D5      ;<<< Store data (BYTE) to send to port in D5

    LEA     PortMsg2,A2   ;'Send to Port xxxx'
    BSR      PRINT_STRING
    MOVE.L   D4,D6        ;Display Port value (as a word)
    MOVE.B   #'H',D1     ;'H'
    BSR      PUTCHAR

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VERIFY_RAM:
    BSR      GETLONG_D7          ;M Command. Verify two RAM locations have the same data
    CMP.B   #' , ' , D2          ;Get start address
    BNE     ERROR               ;Is it valid
    MOVE.L  D7 , A3             ;--- Save in A3

    BSR      GETLONG_D7          ;End address
    CMP.B   #' , ' , D2          ;Is it valid
    BNE     ERROR               ;--- Save in A4
    MOVE.L  D7 , A4             ;--- Save in A4

    CMP.L   A3 , A4             ;If the same nothing to display
    BEQ     LOOP                ;Else swap values
    BGE     VERIFY_OK
    MOVE.L  A3 , A5             ;Else swap values
    MOVE.L  A4 , A3             ;--- Save in A5
    MOVE    A5 , A4

VERIFY_OK:
    ADD.L  #1 , A4              ;End + 1
    BSR    GETLONG_D7           ;End address
    CMP.B  #CR , D2             ;Is it valid
    BNE    ERROR               ;--- Save in A5
    MOVE.L  D7 , A5

VERIFY_OK1: CMP.B  (A3) + , (A5) +
    BNE    BAD_MATCH

VERIFY_OK2: CMP.L  A3 , A4          ;Are we done yet
    BGE    VERIFY_OK1
    BRA    LOOP

BAD_MATCH:
    BSR    CRLF                ;New line
    MOVE.L A3 , D7              ;Backup to problem
    SUBQ.L #1 , D7              ;Show first address
    MOVE.L D7 , A3
    BSR    PUTLONG_D7
    MOVE.B #BLANK , D1
    BSR    PUTCHAR
    MOVE.B (A3) + , D6
    BSR    PUTBYTE_D6
    MOVE.B #BLANK , D1

    BSR    PUTCHAR
    BSR    PUTCHAR

    MOVE.L A5 , D7              ;Backup to problem
    SUBQ.L #1 , D7              ;Show first address
    MOVE.L D7 , A5
    BSR    PUTLONG_D7
    MOVE.B #BLANK , D1
    BSR    PUTCHAR
    MOVE.B (A5) + , D6
    BSR    PUTBYTE_D6
    BSR    CRLF
    BRA    VERIFY_OK2

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;-----

ECHO_ASCII:
    LEA    ECHO_MSG , A2          ;E Command. Get ASCII typed on keyboard and display on screen
    BSR    PRINT_STRING          ;;"Will echo each keyboard char on screen"

ECHO2:
    BSR    CRLF                ;New line
    CLR.L  D1                  ;Just to be on the safe side
    BSR    GETCHAR              ;get a character

    CMP.B  #ESC , D1            ;If ESC then we abort
    BEQ    LOOP

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        BSR      CRLF
        MOVE.W #\$2000,SR          ;Allow ALL INTERRUPTS, SUPERVISOR MODE
INT_LOOP:   MOVE.B #'.' ,D1          ;Continously print .....
        BSR      PUTCHAR
        BSR      GETSTAT
        BEQ     INT_LOOP
        BSR      GETCHAR
        CMP.B  #ESC,D1           ;Echo character
        BEQ     INT_LOOP1
        BSR      TOUPPER
        BSR      PUTCHAR
        BRA     INT_LOOP
        MOVE.W #\$2700,SR          ;MASK OFF INTERRUPTS
        BSR      CRLF
        BRA     START             ;Reload Monitor

LOW_RAM_INITILIZE:
        MOVE.L #\$8,A2            ;Skip (Reset vectors) STACK & ADDRESS vectors etc.
        LEA     BUS_ERROR,A3       ;8H = BUS ERROR
        MOVE.L A3,(A2)+           ;CH = ADDRESS
        LEA     ADDRESS_ERROR,A3
        MOVE.L A3,(A2)+           ;CH = ADDRESS
        LEA     ILLEGAL_ERROR,A3
        MOVE.L A3,(A2)+           ;CH = ADDRESS
        LEA     ZERO_ERROR,A3
        MOVE.L A3,(A2)+           ;CH = ADDRESS
        LEA     ILLEGAL_ERROR,A3
        MOVE.L A3,(A2)+           ;CH = ADDRESS
        LEA     ILLEGAL_ERROR,A3
        MOVE.L A3,(A2)+           ;CH = ADDRESS
        LEA     PRIVILEGE_ERROR,A3
        MOVE.L A3,(A2)+           ;CH = ADDRESS
        LEA     TRACE_ERROR,A3
        MOVE.L A3,(A2)+           ;CH = ADDRESS

        MOVE.L #\$28,A2            ;General Error, Starting at 1010 Illegal Opcode
        LEA     ABORTE,A3          ;Use default Error message
INIT0:    MOVE.L A3,(A2)+           ;Continue up to Spurious Interrupt (60H)
        CMPA.L #\$60,A2
        BMI.S  INIT0

        LEA     SPURIOUS_INT,A3    ;Spurious Interrupt vector
        MOVE.L A3,(A2)+           ;Hardware Interrupts
        LEA     L1_INTERRUPT,A3
        MOVE.L A3,(A2)+           ;Hardware Interrupts
        LEA     L2_INTERRUPT,A3
        MOVE.L A3,(A2)+           ;Hardware Interrupts
        LEA     L3_INTERRUPT,A3
        MOVE.L A3,(A2)+           ;Hardware Interrupts
        LEA     L4_INTERRUPT,A3
        MOVE.L A3,(A2)+           ;Hardware Interrupts
        LEA     L5_INTERRUPT,A3
        MOVE.L A3,(A2)+           ;Hardware Interrupts
        LEA     L6_INTERRUPT,A3
        MOVE.L A3,(A2)+           ;Hardware Interrupts
        LEA     L7_INTERRUPT,A3
        MOVE.L A3,(A2)+           ;Hardware Interrupts

IFEQ SIMMULATOR
INIT1:    LEA     TRAPS,A3          ;If SIMMULATOR = 0, i.e. we are in S100 or ROM mode, w
        MOVE.L A3,(A2)+           ;16 Trap vectors
        CMPA.L #\$C0,A2
        BMI.S  INIT1
ENDC      MOVE.L #\$C0,A2          ;Up to C0H
        LEA     ABORTE,A3          ;Just to be sure we are at the correct place
INIT2:    MOVE.L A3,(A2)+           ;Use default Error message
        ;INITIALIZE VECTORS

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        MOVEM.L (A7) +,D0-D7/A0-A6           ; POP ALL REGISTERS
        RTE

L3_INTERRUPT:
        MOVEM.L D0-D7/A0-A6,-(A7)          ; SAVE ALL REGISTERS
        LEA      L3_INTERRUPT_MSG,A2
        BSR      PRINT_STRING
        MOVEM.L (A7) +,D0-D7/A0-A6         ; POP ALL REGISTERS
        RTE

L4_INTERRUPT:
        MOVEM.L D0-D7/A0-A6,-(A7)          ; SAVE ALL REGISTERS
        LEA      L4_INTERRUPT_MSG,A2
        BSR      PRINT_STRING
        MOVEM.L (A7) +,D0-D7/A0-A6         ; POP ALL REGISTERS
        RTE

L5_INTERRUPT:
        MOVEM.L D0-D7/A0-A6,-(A7)          ; SAVE ALL REGISTERS
        LEA      L5_INTERRUPT_MSG,A2
        BSR      PRINT_STRING
        MOVEM.L (A7) +,D0-D7/A0-A6         ; POP ALL REGISTERS
        RTE

L6_INTERRUPT:
        MOVEM.L D0-D7/A0-A6,-(A7)          ; SAVE ALL REGISTERS
        LEA      L6_INTERRUPT_MSG,A2
        BSR      PRINT_STRING
        MOVEM.L (A7) +,D0-D7/A0-A6         ; POP ALL REGISTERS
        RTE

L7_INTERRUPT:
        MOVEM.L D0-D7/A0-A6,-(A7)          ; SAVE ALL REGISTERS
        LEA      L7_INTERRUPT_MSG,A2
        BSR      PRINT_STRING
        MOVEM.L (A7) +,D0-D7/A0-A6         ; POP ALL REGISTERS
        RTE

ABORTE:
        MOVEM.L D0-D7/A0-A6,-(A7)          ; SAVE ALL REGISTERS
        LEA      INT_ERR_MSG,A2
        BSR      PRINT_STRING
        MOVEM.L (A7) +,D0-D7/A0-A6         ; POP ALL REGISTERS
        RTE

TRAPS:
        MOVEM.L D0-D7/A0-A6,-(A7)          ; SAVE ALL REGISTERS
        LEA      TRAPS_ERR_MSG,A2
        BSR      PRINT_STRING
        MOVEM.L (A7) +,D0-D7/A0-A6         ; POP ALL REGISTERS
        RTE

;-----
TIME:
        LEA      TIME_MSG,A2             ; Time determination module not written yet
        BSR      PRINT_STRING
        BRA      LOOP

;-----

JMP_Z80:
        MOVE.L #SW68K ,D5              ; Switch back to Z80 Master CPU
        MOVE.L D5,A2                  ; Point to status Port 0ECH for DMA1 switch line

        MOVE.B #00,(A2)                ; Currently will use TMA line #1 to switch in/out the 6
        NOP                            ; <-- 68K Is held in HALT mode here until released again
        NOP
        NOP
        NOP
        BRA      LOOP

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```
MOVE.W D2, (A3)
MOVE.W D2, (A3)
BRA    WR_TEST1
;Must Hit Reset button to abort
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```
PATCH:
LEA    PATCH_MSG,A2
BSR    PRINT_STRING
;Y Command, Quick patch to move RAM 4000H-9000H to F4000H-9000H
;Moving Code 4000H-9000H to F4000H, Then jump to that
;The CPM3/Z80 SID program will place any test .bin file
;in RAM (no matter what its final ORG is).
;Get character in D1
BSR    GETCHAR
BSR    TOUPPER
CMP.B #CR,D1
BEQ    PATCH0
BRA    LOOP

PATCH0:
BSR    CRLF
MOVE.L #$4000,A3
MOVE.L #$F4000,A5
MOVE.L #$8000,D1
;Start patch
;This command will then move test versions of this monitor
;program) up out of the way to F4000H and execute it from there
;This should be large enough for a monitor copy

PATCH1:
MOVE.B (A3)+, (A5) +
SUBQ.L #1,D1
BNE    PATCH1
JMP    Patch_RAM
;Jump to this location ($00F40000)
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----- MAIN IDE DRIVE DIAGNOSTIC MENU -----
; Normally the DMA buffers will reside in the RAM on the 68K board itself at 00FD9000H
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```
MY_IDE:
BSR    CLEAR_ID_BUFFER
;Clear ID Buffer
BSR    SEL_DRIVE_A
;Select the first Drive/CF card
BSR    IDEinit
;Initialize the board and drive 0. If there is no drive
BEQ    INIT1_OK
;INIT1_OK:
LEA    INIT_1_ERROR,A2
BSR    PRINT_STRING
BRA    LOOP
BSR    SEL_DRIVE_B
;Select the second Drive/CF card (Do not mess with CPM)
BSR    IDEinit
;Initialize drive 1. If there is no drive abort
BEQ    INIT2_OK
BSR    CLEAR_ID_BUFFER
;Clear ID Buffer
LEA    INIT_2_ERROR,A2
BSR    PRINT_STRING
;Warn second IDE drive did not initialize
INIT2_OK:
BSR    SEL_DRIVE_A
;Back to first drive/CF Card
BSR    DRIVE_ID
;Get the drive 0 id info. If there is no drive just abort
BEQ    INIT3_OK
LEA    BAD_DRIVE,A2
BSR    PRINT_STRING
BRA    LOOP
INIT3_OK:
LEA    IDE_Buffer+12,A2
CMP.W #0, (A2)
BNE    INIT4_OK
;Set default position will be first sector block
;Is it non zero
;If there are zero sectors then something wrong
```

```

        BRA      IDE_LOOP           ;Back to IDE Menu

SET_DRIVE_B:
        BSR      SEL_DRIVE_B       ;Select First Drive
        BRA      IDE_LOOP          ;Back to IDE Menu

SEL_DRIVE_A:
        LEA      IDE_SEL_A,A2     ;Select First Drive
        BSR      PRINT_STRING
        CLR.B   D1                ;Say so

SELECT_DRIVE:
        MOVE.B  D1,CURRENT_IDE_DRIVE
        MOVE.B  D1,IDEDrivePort    ;Select Drive 0 or 1
        RTS

SEL_DRIVE_B:
        LEA      IDE_SEL_B,A2     ;Select Drive 1
        BSR      PRINT_STRING
        MOVE.B  #1,D1              ;Say so
        JMP      SELECT_DRIVE

DRIVE_ID:
        BSR      IDEwaitnotbusy
        BGE      L_5
        CLR      D1
        SUBQ.B #1,D1              ;NZ if error
        RTS      ;If Busy return NZ

L_5:
        MOVE.B  #COMMANDid,D4
        MOVE.B  #REGcommand,D5
        BSR      IDEwr8D          ;Issue the command

        BSR      IDEwaitdrq        ;Wait for Busy=0, DRQ=1
        BGE      L_6
        BRA      SHOWerrors

L_6:
        CLR.B   D6                ;256 words

        LEA      IDE_Buffer,A2     ;Store data here
        BSR      MoreRD16          ;Get 256 words of data from REGdata port to IDE_Buffer

        LEA      msgmdl,A2         ;Decode Drive INFO
        BSR      PRINT_STRING      ;Drive/CF Card Information:-

        LEA      IDE_Buffer+54,A2   ;@ Word 27
        MOVE.B  #20,D3             ;Character count in words
        BSR      Print_ID_Info     ;Print [A2], [D3] X 2 characters
        BSR      CRLF

        LEA      msgsn,A2          ;print the drive's serial number
        BSR      PRINT_STRING      ;'S/N:  '
        LEA      IDE_Buffer+20,A2   ;@ Word 10
        MOVE.B  #10,D3             ;Character count in words
        BSR      Print_ID_Info
        BSR      CRLF

        LEA      msgrev,A2          ;'Rev:  '
        BSR      PRINT_STRING
        LEA      IDE_Buffer+46,A2   ;@ Word 23
        MOVE.B  #4,D3              ;Character count in words
        BSR      Print_ID_Info
        BSR      CRLF

        LEA      msgcy,A2           ;Print the drive's cylinder, head, and sector spec
        BSR      PRINT_STRING      ;'Cylinders:  '
        LEA      IDE_Buffer+2,A2    ;@ Word 1
        BSR      Print_ID_Hex

```

```

    CMP.B  #'Y',D1
    BEQ    WR_SEC_OK1
    BSR    CRLF
    BRA    IDE_LOOP
                                ;Here if there was a problem
                                ;Back to IDE Menu

WR_SEC_OK1: BSR    CRLF
    LEA    IDE_BUFFER,A4
    MOVE.L A4,(RAM_DMA)           ;DMA initially to IDE_Buffer

    BSR    WRITESECTOR            ;Will write whatever is in the IDE_Buffer

    BEQ    Main2B
    BSR    CRLF
    BRA    IDE_LOOP
                                ;Here if there was a problem
                                ;Back to IDE Menu

Main2B:   LEA    msgwr,A2
    BSR    PRINT_STRING          ;Sector written OK

    LEA    IDE_BUFFER,A4
    MOVE.L A4,(RAM_DMA)           ;DMA initially to IDE_Buffer
    BSR    DISPLAY_SECTOR
    LEA    CR_To_Continue,A2
    BSR    PRINT_STRING
    BSR    GETCHAR
    BSR    CRLF
    BRA    IDE_LOOP             ;Back to IDE Menu

```

;----- Fill a sector with a Byte Value (in D5)

```

FILL_SEC:  LEA    FILL_BYTE_MSG,A2      ;Enter sector Fill byte
    BSR    PRINT_STRING
    BSR    GETBYTE_D7            ;Get data in D7 (0-FF)
    CMP.B #ESC,D2              ;If ESC then we are done
    BEQ    IDE_LOOP
    CMP.B #CR,D2                ;If CR then we are done
    BNE    IDE_LOOP
    MOVE.L D7,D5                ;<<< Store data (BYTE) in D5

    LEA    CONFIRM_WR_MSG,A2    ;Are you sure?
    BSR    PRINT_STRING
    BSR    GETCHAR
    BSR    TOUPPER
    CMP.B #'Y',D1
    BEQ    CLEAR_BUFFER
    BSR    CRLF
    BRA    IDE_LOOP             ;Here if abort
                                ;Back to IDE Menu

```

```

CLEAR_BUFFER:
    LEA    IDE_Buffer,A2
    MOVE.W #512,D2
    CLEAR0: MOVE.B D5,(A2)+           ;512 bytes total to fill
    SUBQ.W #1,D2
    BNE    CLEAR0

    LEA    IDE_BUFFER,A4
    MOVE.L A4,(RAM_DMA)           ;DMA initially to IDE_Buffer

    BSR    WRITESECTOR            ;Will write whatever is in the IDE_Buffer

    BEQ    CLEAR2
    BSR    CRLF
    BRA    IDE_LOOP
                                ;Here if there was a problem
                                ;Back to IDE Menu

CLEAR2:   LEA    msgwr,A2
    BSR    PRINT_STRING          ;Sector written OK

    LEA    IDE_BUFFER,A4

```

```

LEA      CONTINUE_MSG,A2           ;If an error ask if we wish to continue
BSR      PRINT_STRING
BSR      GETCHAR
BSR      TOUPPER
CMP.B   #ESC,D1                 ;Abort if ESC
BNE     SEQOK
BSR      CRLF
BRA     IDE_LOOP                ;Back to IDE Menu

SEQOK:    BSR      DISPLAY_POSITION        ;Display current Track,sector,head#
          LEA      IDE_BUFFER,A4
MOVE.L  A4,(RAM_DMA)             ;DMA initially to IDE_Buffer
          BSR      DISPLAY_SECTOR
          BSR      GETSTAT            ;Any keyboard character will stop display
BEQ     NO_WAIT
BSR      GETCHAR
LEA      CONTINUE_MSG,A2
BSR      PRINT_STRING
BSR      GETCHAR
BSR      TOUPPER
CMP.B   #ESC,D1
BNE     NO_WAIT
BSR      CRLF
BRA     IDE_LOOP                ;Back to IDE Menu

NO_WAIT:   BSR      GET_NEXT_SECT        ;Point LBA to next sector
BEQ     MORE_SEC               ;Note will go to last sec on disk unless stopped
BSR      CRLF
BRA     IDE_LOOP                ;Back to IDE Menu

```

;----- Read N Sectors to disk -----  
;Note unlike the normal sector read, this routine increments the DMA address after each sector read

```

N_RD_SEC:  LEA      WILL_RD_MSG,A2        ;Enter RAM location where sector data will be placed
BSR      PRINT_STRING
          BSR      GETLONG_D7        ;Get start address
CMP.B   #CR,D2                 ;Is it valid
BNE     IDE_LOOP
MOVE.L  D7,(RAM_DMA_STORE)      ;<--- Save in RAM_DMA_STORE
          LEA      SEC_COUNT_MSG,A2
          BSR      PRINT_STRING
          BSR      GETBYTE_D7        ;Get data in D7 (0-FF)
CMP.B   #ESC,D2               ;If ESC then we are done
BEQ     IDE_LOOP
CMP.B   #CR,D2               ;If CR then we are done
BNE     IDE_LOOP
MOVE.W  D7,(SECTOR_COUNT)      ;store sector count
BSR      CRLF
BSR      CRLF

```

```

NextRSec:  BSR      DISPLAY_POSITION        ;Display current Track,sector
          LEA      READN_MSG,A2
          BSR      PRINT_STRING
          MOVE.L  (RAM_DMA_STORE),D1
MOVE.L  D1,(RAM_DMA)             ;DMA initially to IDE_Buffer
MOVE.L  D1,D7
          BSR      PUTLONG_D7        ;Show current address

```

```

LEA      WRITEN_MSG,A2          ;' ----> ',0
BSR      PRINT_STRING
BSR      DISPLAY_POSITION       ;Display current Track,sector

BSR      WRITESECTOR           ;Sector/track values are sent to board in WRITESEC

MOVE.L  (RAM_DMA),D1
ADD.L  #$200,D1
MOVE.L  D1,(RAM_DMA_STORE)

SUBQ.W #1,(SECTOR_COUNT)
BNE    NEXT_SEC_NWR
BRA    DoneWSec

NEXT_SEC_NWR:
BSR      GET_NEXT_SECT
BEQ    NextWSec

LEA      AT_END_MSG,A2         ;Tell us we are at end of disk
BSR      PRINT_STRING

DoneWSec:
BSR      CRLF
MOVE.B  #0,(RAM_SEC)          ;Back to CPM sector 0
MOVE.B  #0,(RAM_TRK)
MOVE.B  #0,(RAM_TRK+1)
BSR      WR_LBA                ;Update LBA on drive
BSR      CRLF
BRA    IDE_LOOP               ;Back to IDE Menu

;----- Format current disk-----
FORMAT:   CMP.B   #0,(CURRENT_IDE_DRIVE)
          BNE    FORM_B
          LEA    FORMAT_MSG_A,A2
          BRA    FORM_X
FORM_B:   LEA    FORMAT_MSG_B,A2
FORM_X:   BSR    PRINT_STRING
          LEA    CONFIRM_WR_MSG,A2      ;Are you sure?
          BSR    PRINT_STRING
          BSR    GETCHAR
          BSR    TOUPPER
          CMP.B  #'Y',D1
          BEQ    FORMAT_BUFFER
          BSR    CRLF
          BRA    IDE_LOOP             ;Back to IDE Menu

FORMAT_BUFFER:
          LEA    FORMAT_STARTED_MSG,A2 ;The current drive is being formatted. Esc to abort
          BSR    PRINT_STRING
          BSR    CRLF
          MOVE.B #0,(RAM_SEC)          ;Back to CPM sec_TRK)
          MOVE.B #0,(RAM_TRK+1)

          BSR    WR_LBA                ;Update LBA on drive

          MOVE.W #$0E5E5,D5            ;First set Sector pattern to E5's
          LEA    IDE_Buffer,A2
          MOVE.W #512,D2                ;512 bytes total to fill
CLEARF:   MOVE.B  D5,(A2)+
          SUBQ.W #1,D2
          BNE    CLEARF

FORMAT_LOOP:
          LEA    IDE_BUFFER,A4
          MOVE.L A4,(RAM_DMA)          ;DMA initially to IDE_Buffer
          BSR    WRITESECTOR           ;Will write whatever is in the IDE_Buffer

```

```

MOVE.L A4, (RAM_DMA) ;DMA initially to IDE_Buffer
BSR READSECTOR ;Get sector data from A: drive to buffer
MOVE.B #1,D1 ;Login drive B:
BSR SELECT_DRIVE
BSR WR_LBA ;Update LBA on "B:" drive
LEA IDE_BUFFER,A4
MOVE.L A4, (RAM_DMA)

BSR WRITESECTOR ;Write buffer data to sector on B: drive
BEQ COPY_OK1

LEA COPY_ERR,A2 ;Indicate an error
BSR PRINT_STRING
BSR SHOW_TRACK_SEC ;Show current location of error
BSR CRLF
BRA COPY_OK3

COPY_OK1:
CMP.B #0, (RAM_SEC) ;Get Current Sector
BNE COPY_OK2

BSR SHOW_TRACK

COPY_OK2:
BSR GETSTAT ;Any keyboard character will stop display
BEQ C_NEXTSEC1
BSR GETCHAR ;Flush character

COPY_OK3:
LEA CONTINUE_MSG,A2
BSR PRINT_STRING
BSR GETCHAR
CMP.B #ESC,D1
BNE C_NEXTSEC1
MOVE.B #0,D1 ;Login drive A:
BSR SELECT_DRIVE
MOVE.B D1, (CURRENT_IDE_DRIVE)
MOVE.B #0, (RAM_SEC) ;Start with CPM sector 0
MOVE.B #0, (RAM_TRK) ;Start with CPM Track 0
MOVE.B #0, (RAM_TRK+1)
BSR WR_LBA ;Update LBA on drive
BSR CRLF
BRA IDE_LOOP ;Back to IDE Menu

C_NEXTSEC1:
BSR GET_NEXT_SECT ;Update to next sector/track
BNE C_NEXTSEC2
BRA NextDCopy

C_NEXTSEC2:
LEA CopyDone,A2 ;Tell us we are all done.
BSR PRINT_STRING
BRA C_DONE

;----- Verify Drive A: = B: -----
VERIFY_AB:
LEA DiskVerifyMsg,A2
BSR PRINT_STRING

MOVE.B #0, (RAM_SEC) ;Start with CPM sector 0
MOVE.B #0, (RAM_TRK) ;Start with CPM Track 0
MOVE.B #0, (RAM_TRK+1)
BSR CRLF
BSR CRLF

```

```

MOVE.B #0, (RAM_SEC) ;Start with CPM sector 0
MOVE.B #0, (RAM_TRK) ;Start with CPM Track 0
MOVE.B #0, (RAM_TRK+1)
BSR WR_LBA ;Update LBA on drive
BSR CRLF
BRA IDE_LOOP ;Back to IDE Menu

;----- Back to parent 68K Monitor commands
QUIT_IDE:
    BRA LOOP ;Back to main Menu

;===== Support Routines FOR IDE MODULE =====
;Generate an LBA sector number with data input from CPM style Track# & Sector#
GEN_HEX32_LBA:
    LEA ENTERRAM_SECL,A2 ;Enter sector number, low
    BSR PRINT_STRING
    BSR GETBYTE_D7 ;Get 8 bit value (2 digits) to D7
    MOVE.B D7, (RAM_SEC)
    BSR CRLF

    LEA ENTERRAM_TRKL,A2 ;Enter low byte track number
    BSR PRINT_STRING
    BSR GETBYTE_D7 ;Get 8 bit value (2 digits) to D7
    MOVE.B D7, RAM_TRK
    BSR CRLF

    LEA ENTERRAM_TRKH,A2 ;Enter high byte track number
    BSR PRINT_STRING
    BSR GETBYTE_D7 ;Get 8 bit value (2 digits) to D7
    MOVE.B D7, (RAM_TRK+1)
    CLR.B D1 ;To return NC
    RTS

DISPLAY_POSITION:
    LEA msgCPMTRK,A2 ;Display current track,sector & head position
    BSR PRINT_STRING ;Display in LBA format
    ;---- CPM FORMAT ----
    MOVE.B (RAM_TRK+1),D6
    BSR PUTBYTE_D6 ;High TRK byte
    MOVE.B (RAM_TRK),D6
    BSR PUTBYTE_D6 ;Low TRK byte

    LEA msgCPMSEC,A2 ;SEC = (16 bits)
    BSR PRINT_STRING ;High Sec
    ;---- LBA FORMAT ----
    MOVE.B (RAM_SEC+1),D6
    BSR PUTBYTE_D6 ;Low Sec

    LEA msgLBA,A2 ;(LBA = 00 (<-- Old "Heads" = 0 for these drives).
    BSR PRINT_STRING

    MOVE.B (DISPLAY_TRK+1),D6 ;High "cylinder" byte
    BSR PUTBYTE_D6
    MOVE.B (DISPLAY_TRK),D6 ;Low "cylinder" byte
    BSR PUTBYTE_D6

    MOVE.B (DISPLAY_SEC),D6
    BSR PUTBYTE_D6
    LEA MSGBracket,A2 ; ) $
    BSR PRINT_STRING
    RTS

```

```

Sloop4:      MOVE.B   D6,D1
              BSR      PUTCHAR
              SUBQ.B  #1,D4
              BNE     Sloop2
              BSR      CRLF

              SUBQ.B  #1,D3
              BNE     SF172
              RTS

;Point to next sector. Ret Z if all OK, NZ if at
GET_NEXT_SECT:
              ADDQ.B  #1,(RAM_SEC)
              CMP.B   #MAXSEC-1,(RAM_SEC)
              BNE     NEXT_SEC_DONE

              MOVE.B   #0,(RAM_SEC)           ;Back to CPM sector 0

              ADDQ.B  #1,(RAM_TRK)
              MOVE.B   #0,(RAM_TRK+1)
              CMP.B   #0,(RAM_TRK)
              BEQ     AT_DISK_END

NEXT_SEC_DONE:
              BSR      WR_LBA
              EOR.B   D1,D1
              RTS

AT_DISK_END:
              BSR      WR_LBA
              EOR.B   D1,D1
              SUBQ.B  #1,D1
              RTS           ;;Ret NZ if end of disk

;Point to previous sector. Ret Z if all OK
GET_PREV_SECT:
              CMP.B   #0,(RAM_SEC)
              BEQ     PREVIOUS_TRACK
              SUBQ.B  #1,(RAM_SEC)
              BRA     PREVIOUS_SEC_DONE

PREVIOUS_TRACK:
              MOVE.B   #MAXSEC-1,(RAM_SEC)    ;Back to CPM last sector on previous track

              CMP.B   #0,(RAM_TRK)
              BEQ     AT_00
              SUBQ.B  #1,(RAM_TRK)
              MOVE.B   #0,(RAM_TRK+1)

PREVIOUS_SEC_DONE:
              BSR      WR_LBA
              EOR.B   D1,D1
              RTS

AT_00:
              BSR      WR_LBA
              LEA     ATHOME_MSG,A2
              BSR      PRINT_STRING
              EOR.B   D1,D1
              SUBQ.B  #1,D1
              RTS           ;Update the LBC pointer
;Ret z if all OK
;Update the LBC pointer

;SHOWerrors:
              BSR      CRLF
              MOVE.B   #REGstatus,D5        ;Get status in status register
              BSR      IDErd8D
              MOVE.B   D4,D6
              BTST    #0,D4
              BNE     MoreError             ;Error bit
;Go to REGerr register for more info
;All OK if 01000000

```

```

=====
; IDE Drive BIOS Routines written in a format that can be used with CPM68K throughout we
; will use IDE_BUFFER so the the buffers can reside at the top segment of available RAM.
; Normally this will be FD8100H (Above the ROM).
=====

IDEinit:                                ;Initilize the 8255 and drive then do a hard re
                                         ;;By default the drive will come up initilized

    MOVE.B #READcfg8255,IDECtrlPort      ;Config 8255 chip, READ mode

    MOVE.B #0,IDEportC                  ;No IDE control lines asserted
    MOVE.W #$20,D1                      ;time delay for reset/initilization

InitDelay:                               ;Delay
    SUBQ.W #1,D1
    BNE    InitDelay

    MOVE.B #IDERstline,IDEportC        ;Hard reset the disk drive

    MOVE.W #IDE_Reset_Delay,D1        ;Time delay for reset/initilization (~66 uS, with

ResetDelay:                            ;Delay (IDE reset pulse width)
    SUBQ.W #1,D1
    BNE    ResetDelay

    MOVE.B #0,IDEportC                ;No IDE control lines asserted

    BSR    DELAY_32                  ;Allow time for CF/Drive to recover

    MOVE.B #%11100000,D4              ;Data for IDE SDH reg (512bytes, LBA mode,single d
                                         ;;For Trk,Sec,head (non LBA) use 10100000 (This is
                                         ;;Note. Cannot get LBA mode to work with an old Sea
                                         ;;have to use the non-LBA mode. (Common for old har
                                         ;00001110,(0EH) for CS0,A2,A1,
                                         ;Write byte to select the MASTER device

    MOVE.B #REGshd,D5
    BSR    IDEwr8D

    MOVE.B #$FF,D6                  ;<<< May need to adjust delay time

WaitInit:                               ;Get status after initialization
                                         ;Check Status (info in [DH])

    MOVE.B #REGstatus,D5
    BSR    IDErd8D
    MOVE.B D4,D1
    AND.B #$80,D1
    BEQ    DoneInit                 ;Return if ready bit is zero

    MOVE.L #$0FFF,D7
    MOVE.B #2,D5
    SUBQ.B #1,D5
    BNE    DELAY1                  ;May need to adjust delay time to allow cold drive
                                         ;to speed

DELAY1:                                 ;RET WITH NZ FLAG SET IF ERROR (PROBABLY NO DRIVE)

    SUBQ.B #1,D7
    BNE    DELAY2

    SUBQ.B #1,D6
    BNE    WaitInit
    BSR    SHOWerrors
    RTS                           ;Ret with NZ flag set if error (probably no drive)

DoneInit:                             ;EOR D1,D1
                                         ;RTS

DELAY_32:                                ;DELAY ~32 MS (DOES NOT SEEM TO BE CRITICAL)

    MOVE.B #40,D1
    MOVE.B #0,D2
    SUBQ.B #1,D2
    BNE    M0
    SUBQ.B #1,D1
    BNE    DELAY3
    RTS

M0:                                     ;Read a sector, specified by the 4 bytes in LBA
                                         ;Z on success, NZ BSR error routine if problem
                                         ;Tell which sector we want to read from.
                                         ;Note: Translate first in case of an error otherew

DELAY3:                                ;RET WITH NZ FLAG SET IF ERROR (PROBABLY NO DRIVE)

    MOVE.B #40,D1
    MOVE.B #0,D2
    SUBQ.B #1,D2
    BNE    M0
    SUBQ.B #1,D1
    BNE    DELAY3
    RTS

READSECTOR:                            ;Note: Translate first in case of an error otherew

```

```

MOVE.B (A2) +, IDEportB

MOVE.B #REGdata, IDEportC
OR.B #IDEwrline, IDEportC ;Send WR pulse
MOVE.B #REGdata, IDEportC
SUBQ.B #$1, D6
BNE WRSEC1_IDE

MOVE.B #READcfg8255, IDECtrlPort ;Set 8255 back to read mode

MOVE.B #REGstatus, D5
BSR IDErd8D
MOVE.B D4, D1
AND.B #$1, D1
BEQ L_21
BSR SHOWerrors ;If error display status
L_24: RTS

WR_LBA:
MOVE.B (RAM_SEC), D4
ADDQ.B #$1, D4
MOVE.B D4, (DISPLAY_SEC)
MOVE.B #REGsector, D5
BSR IDEwr8D ;LBA mode, Low sectors go directly
;Sectors are numbered 1 -- MAXSEC (even in LBA mode)
;For Diagnostic Display Only
;Send info to drive
;Write to 8255 A Register
;Note: For drive we will have 0 - MAXSEC sectors or numbers etc.

MOVE.B (RAM_TRK), D4 ;Send Low TRK#
MOVE.B D4, (DISPLAY_TRK)
MOVE.B #REGcylinderLSB, D5 ;Write to 8255 A Register
BSR IDEwr8D

MOVE.B (RAM_TRK+1), D4 ;Send High TRK#
MOVE.B D4, (DISPLAY_TRK+1)
MOVE.B #REGcylinderMSB, D5 ;Send High TRK# (in DH) to IDE Drive
BSR IDEwr8D ;Special write to 8255 B Register (Not A) to update
BSR IDEwr8D_X ;High 8 bits ignored by IDE drive

MOVE.B #$1, D4 ;For CPM, one sector at a time
MOVE.B #REGsecCnt, D5 ;Write to 8255 A Register
BSR IDEwr8D

RTS ;Special version for MS-DOS system BIOS (see IBM B
;This will display Head, Cylinder and Sector on the
;instead of LBA sector numbers.
;OR in head info to lower 4 bits
;Just in case
;Set to >>>> NON-LBA mode <<<<
;Send "Head #" (in DH) to IDE drive

DOS_WR_LBA:
MOVE.B CURRENT_HEAD, D4
AND.B #$0F, D4
OR.B #&10100000, D4
MOVE.B #REGshd, D5
BSR IDEwr8D ;Get head info to lower 8 bits of the special
;top two LED HEX displays.
;These 8 (high) data lines are ignored by the IDE
;Will display the Head in top nibble and the two
;of the high cylinder in the low nibble.
;Special output to 8255 B Register (Not A) to upda

MOVE.B CURRENT_TRACK_HIGH, D4 ;Send High TRK#
MOVE.B #REGcylinderMSB, D5 ;Send High TRK# (in DH) to IDE Drive
BSR IDEwr8D

MOVE.B CURRENT_HEAD, D4 ;Get low Track #
AND.B #$0F, D4
LSL #4, D4
OR.B CURRENT_TRACK_HIGH, D4 ;Send Low TRK# (in DH)
MOVE.B #REGcylinderLSB, D5 ;Special write to 8255 B Register (Not A)
BSR IDEwr8D_X

```

```
;-----  
; Low Level 8 bit R/W to the drive controller. These are the routines that talk  
; directly to the drive controller registers, via the 8255 chip.  
; Note the 16 bit Sector I/O to the drive is done directly  
; in the routines READSECTOR & WRITESECTOR for speed reasons.
```

```
IDErD8D:
```

```
    MOVE.B D5, IDEportC           ;READ 8 bits from IDE register @ [DL], return info  
    OR.B #IDERdline, IDEportC    ;Select IDE register, drive address onto control l  
    MOVE.B IDEportA, D4          ;RD pulse pin (40H), Assert read pin  
    MOVE.B D5, IDEportC          ;Return with data in [D4]  
    MOVE.B D5, IDEportC          ;Select IDE register, drive address onto control l  
    MOVE.B #0, IDEportC          ;Zero all port C lines  
    RTS
```

```
IDEwr8D:
```

```
    MOVE.B #WRITEcfg8255, IDECtrlPort ;WRITE Data in [DH] to IDE register @ [DL]  
    MOVE.B D4, IDEportA           ;Set 8255 to write mode  
    MOVE.B D5, IDEportC           ;Get data put it in 8255 A port  
    OR.B #IDEwrline, IDEportC    ;Select IDE register, drive address onto contr  
    MOVE.B D5, IDEportC           ;Assert write pin  
    MOVE.B D5, IDEportC           ;Select IDE register, drive address onto contr  
    MOVE.B #0, IDEportC           ;Zero all port C lines  
    MOVE.B #READcfg8255, IDECtrlPort ;Config 8255 chip, read mode on return  
    RTS
```

```
IDEwr8D_X:
```

```
    MOVE.B #WRITEcfg8255, IDECtrlPort ;WRITE Data in [DH] to IDE register @ [DL]  
    MOVE.B D4, IDEportB           ;Set 8255 to write mode  
    MOVE.B D5, IDEportC           ;Get data and put it in 8255 >>> Port B <<<  
    OR.B #IDEwrline, IDEportC    ;Select IDE register, drive address onto contr  
    MOVE.B D5, IDEportC           ;Assert write pin  
    MOVE.B D5, IDEportC           ;Select IDE register, drive address onto contr  
    MOVE.B #0, IDEportC           ;Zero all port C lines  
    MOVE.B #READcfg8255, IDECtrlPort ;Config 8255 chip, read mode on return  
    RTS
```

```
;----- Routine to download from a PC via XMODEM a .bin file -----
```

```
XMODEM_BIN:
```

```
    LEA     MODEM_BIN_SIGNON, A2      ;Download an XModem .bin file. Note some registers ch  
    BSR     PRINT_STRING            ;Will show message explaining we are about to upload a  
  
    MOVE.B #0, (RECVD_SECT_NO)  
    MOVE.B #0, (SECTNO)  
    MOVE.B #0, (ERRCT)  
  
    BSR     SERIAL_INITILIZE_A      ;RESET THE ZILOG SCC  
  
    LEA     RAM_DESTINATION_MSG, A2  ;Ask for destination  
    BSR     PRINT_STRING  
    BSR     GETLONG_D7              ;Get start address  
    CMP.B #CR, D2                  ;Is it valid - must end with CR
```

```

RHNTO:      CMP.B    #SOH,D1           ;GOT CHAR - MUST BE SOH
            BEQ     GOT_SOH
            OR.B    D1,D1
            BNE     L_2
            BRA     RECV_HDR
L_2:        CMP.B    #EOT,D1
            BNE     L_3
            BRA     GOT_EOT
L_3:        MOVE.B   D1,D6
            BSR     PUTBYTE_D6
            LEA     ERRSOH,A2
            BSR     PRINT_STRING
            BRA     RECV_SECT_ERR

GOT_SOH:
            MOVE.L   #SERIAL_RETRY, D2
            BSR     RECV
            CMP.B   #$FF,D2
            BNE     RECV_HDR_TIMEOUT

            MOVE.B   D1,D5
            MOVE.L   #SERIAL_RETRY, D2
            BSR     RECV
            CMP.B   #$FF,D2
            BNE     RECV_HDR_TIMEOUT
            NOT.B   D1

            CMP.B   D1,D5           ;GOOD SECTOR #?
            BEQ     RECV_SECTOR

            LEA     MODEM_ERR2,A2
            BSR     PRINT_STRING
            BRA     RECV_SECT_ERR

RECV_SECTOR:
            MOVE.B   D5,(RECVD_SECT_NO)
            CLR.B   D4
            MOVE.B   #$80,D3           ;Now get 128 Bytes
                                         ;GET SECTOR #
                                         ;INIT CKSUM = 0
                                         ;128 Byte sectors always

RECV_CHAR:
            MOVE.L   #20*SERIAL_RETRY, D2
            BSR     RECV
            CMP.B   #$FF,D2
            BNE     RECV_HDR_TIMEOUT
            MOVE.B   D1,(A3)+          ;Number of times to try reading serial port before abort
                                         ;<<< STORE CHAR >>>
            ADD.B   D1,D4
            SUB.B   #1,D3
            BNE     RECV_CHAR          ;Add in checksum
                                         ;128 Bytes done yet?

            MOVE.L   #SERIAL_RETRY, D2
            BSR     RECV
            CMP.B   #$FF,D2
            BNE     RECV_HDR_TIMEOUT  ;NEXT VERIFY CHECKSUM
                                         ;Number of times to try reading serial port before abort
                                         ;GET CHECKSUM
                                         ;Return with FF in D2 if all is OK

MODL_5:
            CMP.B   D1,D4
            BNE     RECV_CKSUM_ERR
            MOVE.B   (RECVD_SECT_NO),D2
            ADD.B   #1,D5
            CMP.B   D5,D2
            BNE     DO_ACK             ;CHECK IF CHECKSUM IS CORRECT
                                         ;GOT A SECTOR, WRITE IF = 1+PREV SECTOR
                                         ;CALC NEXT SECTOR #
                                         ;MATCH?

DO_ACK:
            MOVE.B   D5,(SECTNO)       ;UPDATE SECTOR #
            MOVE.B   #ACK,D1
            BSR     SERIAL_OUT
            BRA     RECV_LOOP

RECV_CKSUM_ERR:
            LEA     MODEM_ERR3,A2
            BSR     PRINT_STRING

```

```
MOVE.L  (A7) +, D1  
DONE_LONG: RTS ;Normal return with FFh in D1 if CR or ',' was entered
```

```
GETBYTE_D7: CLR.L  D7 ;Get a Byte number and place in D7 (1-2 bytes)  
BSR     GETLONG_D7 ;Return with just a Byte (D2 will normally be 2)  
AND.L  #$ff, D7  
RTS
```

```
GETNIBBLE: CLR.B  D2 ;clear D2 flag byte  
CLR.B  D1 ;just in case  
BSR    GETCHAR ;Get a HEX character (0,1,2,3...A,B,C,D,E,F in D1)  
CMP.B  #ESC, D1 ;Was an abort requested  
BEQ    NIBBLE1  
  
CMP.B  #CR, D1 ;CR terminates data entry  
BEQ    NIBBLE1  
CMP.B  #', ', D1 ;',' also terminates data entry  
BEQ    NIBBLE1  
CMP.B  #BLANK, D1 ;A BLANK also terminates data entry  
BEQ    NIBBLE1  
  
BSR    TOUPPER ;(D1) Lower case to Upper case  
  
SUB.B  #$30, D1 ;SEE IF LESS THAN ZERO  
BLT.S  NIBBLE2  
  
CMP.B  #$09, D1 ;SEE IF GT 9  
BLE.S  NIBBLE1  
SUBQ.B #7, D1 ;NORMALIZE $A TO 10  
CMP.B  #$10, D1 ;SEE IF TOO LARGE  
BCC.S  NIBBLE2  
RTS    ;Return with nibble in D1 (0,1,2,3...F)  
  
NIBBLE1: MOVE.B  D1, D2 ;Store ESC/CR//BLANK in D2  
RTS
```

```
NIBBLE2: MOVE.B  #BELL, D1 ;Not a valid HEX character  
BSR    PUTCHAR  
MOVE.B  #'?', D1  
BSR    PUTCHAR  
MOVE.B  #ESC, D2  
RTS
```

```
PUTLONG_D7: MOVE.L  D7, D6 ;Print long in D7 on CRT, Note D6 destroyed  
SWAP   D6 ;Swap down upper word  
BSR    PUTWORD_D6  
MOVE.L  D7, D6  
BSR    PUTWORD_D6  
RTS
```

```
PUTWORD_D6: MOVE.W  D6, D1 ;Note D1 is destroyed  
LSR.W  #8, D1 ;Shift upper byte to lower 8 bits  
LSR.W  #4, D1 ;Shift upper byte to lower 4 bits  
AND.B  #$0F, D1 ;SAVE LOWER NIBBLE  
OR.B   #$30, D1 ;CONVERT TO ASCII  
CMP.B  #$39, D1 ;SEE IF IT IS > 9  
BLE.S  HEXOK2  
ADDQ.B #7, D1 ;ADD TO MAKE 10=>A  
BSR    PUTCHAR  
  
MOVE.W  D6, D1 ;Address lower high byte nibble  
LSR.W  #8, D1 ;Origional number again to D1  
AND.B  #$0F, D1 ;Shift upper byte to lower 8 bits  
SAVE LOWER NIBBLE
```

```

        BSR      SERIAL_OUT          ;Call serial output routine
        MOVE.L   (A7)+,A0           ;Restore A0
        MOVE.L   (A7)+,D5           ;Restore D5
        RTS                  ;Return from subroutine, char in D1

PUTCHAR0: MOVE.L   (A7)+,A0          ;< Restore A0
PUTCHAR1: MOVE.B   (A0),D5           ;Check CRT status is ready to receive character
        AND.B   #$04,D5
        TST.B   D5
        BEQ    PUTCHAR1
        MOVE.B   D1,(A1)           ;Output ASCII (in D1) to hardware port 01H
        MOVE.L   (A7)+,D5           ;< Restore D5
        RTS                  ;Return from subroutine

ENDC

;----- MAIN ROUTINE TO GET A CHARACTER FROM CONSOLE -----
;A0 has console status port, A1 has console data port

GETCHAR:
IFNE SIMMULATOR
        MOVE.B   #5,D0             ;If SIMMULATOR = 1, then echo character via software i
        TRAP    #15
        RTS

ENDC

IFEQ SIMMULATOR
        MOVE.L   D5,-(A7)          ;If SIMMULATOR = 0, then echod character via PUTCHAR
        MOVE.L   A0,-(A7)
        MOVE.L   #IOBYTE,A0         ;> Save D5
        MOVE.B   (A0),D5           ;> Save A0
        AND.B   #$20,D5
        TST.B   D5
        BRA    GETCHAR0
        BNE    GETCHAR0
        BSR    SERIAL_IN          ;Point to IOBYTE Port on SMB
        MOVE.L   (A7)+,A0           ;Check if data is to be sent to the serial port
        MOVE.L   (A7)+,D5
        RTS                  ;Return from subroutine, char in D1

;
;       ;Jump to simple Propeller port

        ;Call serial input routine (currently not working!)
        ;Restore A0
        ;Restore D5
        ;Return from subroutine, char in D1

GETCHAR0: MOVE.L   (A7)+,A0          ;< Restore A0 (console status port)
GETCHAR1: MOVE.B   (A0),D5           ;Get a keyboard character in D1
        AND.B   #$02,D5
        TST.B   D5
        BEQ    GETCHAR1
        MOVE.B   (A1),D1           ;Are we ready
        BSR    PUTCHAR
        MOVE.L   (A7)+,D5           ;Get ASCII (in D1) from hardware port 01H
        RTS                  ;Echo it on console
        ;< Restore D5
        ;Return from subroutine, char in D1

ENDC

GETSTAT:  MOVE.B   (A0),D1           ;Get a keyboard status in D1, Z= nothing, 2 = char pre
        AND.B   #$02,D1
        TST.B   D1
        RTS

;----- SERIAL PORT OUTPUT CHARACTER ROUTINE -----

SERIAL_OUT: MOVE.L   D5,-(A7)          ;> Save D5
        MOVE.L   D2,-(A7)
        MOVE.L   A0,-(A7)
        MOVE.L   #ACTL,A0           ;> Save D2
        MOVE.W   #512,D2            ;> Save A0
                                ;Point to Control port of Zilog serial chip
                                ;Will check status 512 times (only)

SERIAL_OUT_STAT:
        MOVE.B   (A0),D5           ;Check serial port is ready
        AND.B   #$04,D5
        TST.B   D5

```

```

CRLF:
    MOVE.B #CR,D1 ;Send CR/LF to CRT
    BSR PUTCHAR
    MOVE.B #LF,D1
    BSR PUTCHAR
    RTS

PUT_TAB:
    MOVE.B #TAB,D1 ;Send TAB to CRT
    BSR PUTCHAR
    RTS

SPACE:
    MOVE.B #BLANK,D1 ;SPACE to CRT
    BSR PUTCHAR
    RTS

TOUPPER:
    CMP.B #$40,D1 ;LC->UC in D1
    BCS UPPER_DONE
    CMP.B #$7B,D1
    BCC UPPER_DONE
    AND.B #$5F,D1
    RTS

UPPER_DONE:
    RTS

ERROR:
    LEA ErrorMsg,A2 ;Show unknown error
    BSR PRINT_STRING
    BRA LOOP

NOT_DONE:
    LEA NotDoneMsg,A2 ;Code not done yet
    BSR PRINT_STRING
    BRA LOOP

SPEAKOUT:
    MOVE.L A3,-(A7) ;Send character in D1 to Console IO board speaker
    MOVE.L D2,-(A7) ;> Save A3
    MOVE.L D3,-(A7) ;> Save D2
    MOVE.L #255,D2 ;> Save D3
    MOVE.L #BCTL,A3 ;Will try 255 times, then timeout

SOUT1:
    MOVE.L (A3),D3
    AND.B #$04,D3
    BNE SENDS
    SUB.B #1,D2
    BNE SOUT1

SOUT2:
    MOVE.L (A7)+,D3 ;< Restore D3
    MOVE.L (A7)+,D2 ;< Restore D2
    MOVE.L (A7)+,A3 ;< Restore A3
    RTS

SENGS:
    MOVE.L #BDTA,A3 ;Send actual character to data port
    MOVE.B D1,(A3) ;<---- For debugging, display character ---
    BSR PUTCHAR ;For some reason we need this delay
    MOVE.L #SPEAKER_DELAY,D3 ;If not characters get dropped!
    SENDS1:
    SUB.L #1,D3
    TST.L D3
    BNE SENDS1
    MOVE.B #5,D3
    MOVE.L #BCTL,A3
    MOVE.B D3,(A3)
    MOVE.B #$E8,D3
    MOVE.B D3,(A3)
    BRA SOUT2 ;Sel register 5
                           ;Raise RTS line to prevent the next character arriving

SPEAK_STRING:
    MOVE.B (A2)+,D1 ;ROUTINE TO SEND A STRING IN (A2) TO TALKER, terminate
    CMP.B #0,D1
    TST.B D1
    BEQ SPEAK_DONE
    CMP.B #CR,D1

```

dc.l	QUERY_PORT	;Q ;Query In or Out to a port
dc.l	ERR	;R
dc.l	SUBS_RAM	;S ;Substitute byte values in RAM
dc.l	ASCII_RAM	;T ;Show ASCII values in RAM
dc.l	TEST_SERIAL	;U ;Test serial port
dc.l	VERIFY_RAM	;V ;Verify two memory regions are the same
dc.l	ERR	;W
dc.l	SIGNALS	;X ;Setup for hardware S-100 bus signals test
dc.l	PATCH	;Y ;Quick patch to move RAM 4000H-9000H to F4000H
dc.l	JMP_Z80	;Z ;Return back to Z80 master

IDE_TABLE	dc.l	SET_DRIVE_A	; "A" Select Drive A
	dc.l	SET_DRIVE_B	; "B" Select Drive B
	dc.l	COPY_AB	; "C" Copy Drive A to Drive B
	dc.l	IDE_ERR	; "D"
	dc.l	FILL_SEC	; "E" Fill a sector with a byte value
	dc.l	FORMAT	; "F" Format current disk
	dc.l	IDE_ERR	; "G"
	dc.l	IDE_ERR	; "H"
	dc.l	IDE_ERR	; "I"
	dc.l	IDE_ERR	; "J"
	dc.l	IDE_LOOP	; "K"
	dc.l	SET_LBA	; "L" Set LBA value (Set Track,sector)
	dc.l	IDE_ERR	; "M"
	dc.l	NEXT_SECT	; "N" Next Sector
	dc.l	DRIVE_ID	; "O" Show current Drive ID
	dc.l	PREV_SECT	; "P" Previous sector
	dc.l	IDE_ERR	; "Q"
	dc.l	READ_SEC	; "R" Read sector to data buffer
	dc.l	SEQ_SEC_RD	; "S" Sequential sec read and display contents
	dc.l	IDE_ERR	; "T"
	dc.l	IDE_ERR	; "U"
	dc.l	VERIFY_AB	; "V" Verify Drive A:= Drive B:
	dc.l	WRITE_SEC	; "W" Write data buffer to current sector
	dc.l	N_RD_SEC	; "X" Read N sectors to RAM
	dc.l	N_WR_SEC	; "Y" Write N sectors
	dc.l	IDE_ERR	; "Z"

#### SCCINIT\_A:

	dc.b	\$04	;BOTH CONSOLE IO BOARD's SSC's are set for 19,200
	dc.b	\$44	;Point to WR4
	dc.b	\$03	;X16 clock,1 Stop,NP
	dc.b	\$C1	;Point to WR3
	dc.b	\$E1	;Enable reciever, Auto Enable, Recieve 8 bits
	dc.b	\$05	;Enable reciever, No Auto Enable, Recieve 8 bits (
	dc.b	\$EA	;Point to WR5
	dc.b	\$0B	;Enable, Transmit 8 bits
	dc.b	\$56	;Set RTS,DTR, Enable. Point to WR11
	dc.b	\$0C	;Recieve/transmit clock = BRG
	dc.b	\$40	;Point to WR12
	dc.b	\$1E	;Low Byte 2400 Baud
	dc.b	\$0E	;Low Byte 4800 Baud
	dc.b	\$06	;Low Byte 9600 Baud
	dc.b	\$02	;Low byte 19,200 Baud
	dc.b	\$00	;Low byte 38,400 Baud <<<<<<< XModem I/O
	dc.b	\$0D	;Low byte 76,800 Baud
	dc.b	\$00	;Point to WR13
	dc.b	\$OE	;High byte for Baud
	dc.b	\$01	;Point to WR14
	dc.b	\$0F	;Use 4.9152 MHz Clock. Note SD Systems uses a 2.45
	dc.b	\$00	;Point to WR15
			;Generate Int with CTS going high

#### SCCINIT\_B:

	dc.b	\$04	;Point to WR4
	dc.b	\$44	;X16 clock,1 Stop,NP
	dc.b	\$03	;Point to WR3
	dc.b	\$C1	;Enable reciever, Auto Enable, Recieve 8 bits
	dc.b	\$05	;Point to WR5
	dc.b	\$EA	;Enable, Transmit 8 bits

SERIAL\_TEST\_DONE\_MSG dc.b CR,LF,'Serial test done.',CR,LF,0  
 IDE\_SIGNON0 dc.b CR,LF,LF,'IDE HDisk Test Menu Routines. ',0  
 IDE\_SIGNON1 dc.b 'A=Select Drive A B=Select Drive B E=Fill Sec F=Format Disk',  
 dc.b 'N=Next Sec P=Previous Sec L=Set LBA Value O=Disk ID',CR,L  
 dc.b 'R=Read Sector S=Seq Sec Rd X=Sectors to RAM W=Write Sector.  
 dc.b 'Y=RAM to Sectors C=Copy A->B V=Verify A=B (ESC) Main Menu  
 dc.b CR,LF,'Current settings:- ',0  
 IDE\_MENU\_CMD dc.b 'Enter a Command:- ',0  
 IDE\_HARDWARE dc.b CR,LF,'Initilizing IDE Drive hardware.',0  
 INIT\_1\_ERROR dc.b CR,LF,'Init of First Drive failed.',BELL,CR,LF,LF,0  
 INIT\_2\_ERROR dc.b CR,LF,'Init of Second Drive failed. (Possibly not present).',BELL,CR,LF  
 BAD\_DRIVE: dc.b CR,LF,'First Drive ID Info appears invalid. '  
 dc.b '(Drive possibly not present).',CR,LF  
 dc.b 'Aborting Command.',BELL,CR,LF,LF,0  
 dc.b CR,LF,BELL,'Bad Command!',0  
 NotDoneYet dc.b CR,LF,'CMD Not Done Yet',0  
 CONFIRM\_WR\_MSG dc.b CR,LF,LF,BELL,'Will erase data on the current drive, '  
 dc.b 'are you sure? (Y/N) ...',0  
 msgrd dc.b 'Sector Read OK',CR,LF,0  
 msgwr dc.b 'Sector Write OK',CR,LF,0  
 SET\_LBA\_MSG dc.b 'Enter CPM style TRK & SEC values (in hex).',CR,LF,0  
 ENTERRAM\_SECL dc.b 'Starting sector number, (xxH) = ',0  
 ENTERRAM\_TRKL dc.b 'Track number (LOW byte, xxH) = ',0  
 ENTERRAM\_TRKH dc.b 'Track number (HIGH byte, xxH) = ',0  
 DRIVE\_BUSY dc.b 'Drive Busy (bit 7) stuck high. Status = ',0  
 DRIVE\_NOT\_READY dc.b 'Drive Ready (bit 6) stuck low. Status = ',0  
 DRIVE\_WRFAULT dc.b 'Drive write fault. Status = ',0  
 UNKNOWN\_ERROR dc.b 'Unknown error in status register. Status = ',0  
 BAD\_BLOCK dc.b 'Bad Sector ID. Error Register = ',0  
 UNRECOVER\_ERR dc.b 'Uncorrectable data error. Error Register = ',0  
 READ\_ID\_ERROR dc.b 'Error setting up to read Drive ID',CR,LF,0  
 SEC\_NOT\_FOUND dc.b 'Sector not found. Error Register = ',0  
 INVALID\_CMD dc.b 'Invalid Command. Error Register = ',0  
 TRKO\_ERR dc.b 'Track Zero not found. Error Register = ',0  
 UNKNOWN\_ERROR1 dc.b 'Unknown Error. Error Register = ',0  
 CONTINUE\_MSG dc.b CR,LF,'To Abort enter ESC. Any other key to continue. ',0  
 FORMAT\_MSG\_A dc.b CR,LF,'Format Disk A: with E5Hs',0  
 FORMAT\_MSG\_B dc.b CR,LF,'Format Disk B: with E5Hs',0  
 ATHOME\_MSG dc.b CR,LF,BELL,'Already on Track 0, Sector 0',0  
 AT\_START\_MSG dc.b CR,LF,BELL,'Already at start of disk!',0  
 AT\_END\_MSG dc.b CR,LF,BELL,'At end of Disk!',0  
 READN\_MSG dc.b ' ----> ',0  
 WRITEN\_MSG dc.b 'H ----> ',0  
 DiskCopyMsg dc.b CR,LF,'Copy Drive A to Drive B (Y/N)? ',0  
 DiskVerifyMsg dc.b CR,LF,'Will verify Drive A = Drive B.',0  
 CopyDone dc.b CR,LF,'Disk Copy Done.',0  
 VERIFY\_ERR dc.b CR,LF,BELL,'Verify Error at:- ',0  
 VerifyDone dc.b CR,LF,'Disk Verify Done.',0  
 CR\_To\_Continue dc.b CR,LF,'Hit any key to continue.',0  
 OK\_CR\_MSG dc.b 'OK',CR,LF,0  
 COPY\_ERR dc.b CR,LF,BELL,'Sector Copy Error.',0  
 CURRENT\_MSG\_A dc.b 'Current Drive = A:',0  
 CURRENT\_MSG\_B dc.b 'Current Drive = B:',0  
 FORMAT\_ERR dc.b CR,LF,BELL,'Sector Format Error',0  
 ERR\_MSG dc.b CR,LF,BELL,'Invalid Command (or code not yet done)',CR,LF,0  
 DRIVE1\_MSG dc.b ' on Drive A',CR,LF,0  
 DRIVE2\_MSG dc.b ' on Drive B',CR,LF,0  
 IDE\_SEL\_A dc.b CR,LF,'Selecting IDE Drive A',0  
 IDE\_SEL\_B dc.b CR,LF,'Selecting IDA Drive B',0  
 FORMAT\_STARTED\_MSG dc.b CR,LF,'The current drive is being formatted. Use Esc to abort.',0  
 FILL\_BYTE\_MSG dc.b CR,LF,'Enter Fill byte (+CR) :- ',0  
 MODEM\_BIN\_SIGNON dc.b CR,LF,'Load a .bin File from a PC to RAM using Serial Board',CR,LF  
 dc.b 'Zilog SCC Ports A1H & A3H, 38,400 Baud.',CR,LF,0  
 RAM\_DESTINATION\_MSG dc.b CR,LF,'Enter destination in RAM for data (up to 8 digits): ',0  
 DOWNLOAD\_MSG dc.b 'Downloading file Started.',0  
 RMSG dc.b CR,LF,'WAITING FOR SECTOR #',0

IDE_BUFFER	ds.b	512	<i>;Buffer area for sector data</i>
IDE_BUFFER2	ds.b	512	
RAM_DMA:	dc.w	0	<i>;Storage or DMA address</i>
RAM_DMA_STORE	dc.l	0	
SECTOR_COUNT	dc.w	0	
DISPLAY_TRK	dc.w	0	
DISPLAY_SEC	dc.w	0	
RAM_SEC:	dc.b	0	
RAM_TRK:	dc.b	0	
CURRENT_IDE_DRIVE	dc.b	0	
CURRENT_HEAD	dc.b	0	
CURRENT_TRACK_HIGH	dc.b	0	
CURRENT_TRACK	dc.b	0	
CURRENT_SECTOR	dc.b	0	
SECTORS_TO_DO	dc.b	0	
RECVD_SECT_NO	dc.b	0	<i>;For XMODEM</i>
SECTNO	dc.b	0	<i>; "</i>
ERRCT	dc.b	0	<i>; "</i>
S_FILE_ADDRESS	dc.l	0	<i>;Start location in RAM of S file</i>
EndRAM:	dc.b	0	<i>;End of 0 cleared RAM area</i>
IFEQ SIMMULATOR			<i>;If SIMMULATOR = 0</i>
END		\$00FDFFFF	
ENDC			
IFNE SIMMULATOR			<i>;If SIMMULATOR = 1</i>
END		\$0000	
ENDC			